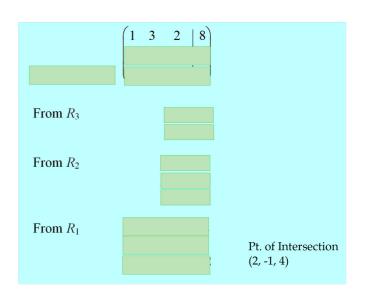
## Vectors

## **Intersection of Three Planes**

Three planes may:

- (1) intersect at a point
- (2) intersect in a line
- (3) not all intersect (only intersect two at a time)

Since each plane has an equation of the form ax + by + cz + d = 0, the intersection is a solution of a 3×3 system of equations.



## [Matrix Revision: Redundancy]

Example (a line of intersection)

Solve the system of equations: 
$$x + y + z = 6$$

$$2x + y - 2z = -2$$
$$3x + 2y - z = 4$$

The row of zeros gives no information ⇒ infinite number of solutions

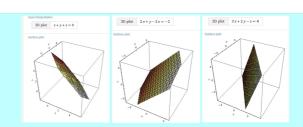
Let z = t, to give the parametric equations

From 
$$R_2$$
:  $-y - 4z = -14 \quad (z = t)$   
 $y = 14 - 4t$ 

From 
$$R_1$$
:  $x + y + z = 6$   $(y = 14 - 4t \text{ and } z = t)$   
 $x + (14 - 4t) + t = 6$   
 $x = 3t - 8$ 

Hence solution can be written x = 3t - 8, y = 14 - 4t, z = t

or in Symmetric Form: 
$$\frac{x+8}{3} = \frac{y-14}{-4} = \frac{z}{1}$$



These equations give points that all lie on a straight line.

The system of equations has an infinite number of solutions.

There are, really, only two equations, & the 3rd is **redundant**.



## [Matrix Revision : Inconsistent]

Example (no intersection)

Solve the system of equations: 
$$x+y+z=6$$
  
 $2x+y-2z=-2$ 

$$x+y+z=6$$

$$2x+y-2z=-2$$

$$3x+2y-z=3$$

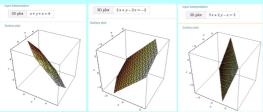
$$\begin{pmatrix}
1 & 1 & 1 & | & 6 \\
2 & 1 & -2 & | & -2 \\
3 & 2 & -1 & | & 3
\end{pmatrix} \qquad R_1 \\
R_2 \\
R_3$$

$$\begin{pmatrix}
1 & 1 & 1 & | & 6 \\
-14 \\
-15
\end{pmatrix}$$

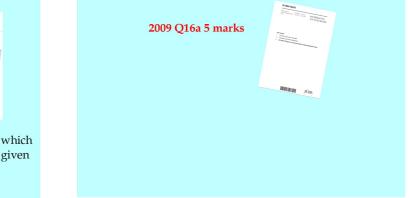
$$\begin{pmatrix}
1 & 1 & 1 & | & 6 \\
-14 \\
-14
\end{pmatrix}$$



All three planes do not intersect.



**Inconsistency** means that there are no values of x, y, z which satisfy all three equations. It arises when three planes, given by the 3 equations, do not have a point in common.



ex15 page 78 Q1ab, 2cd