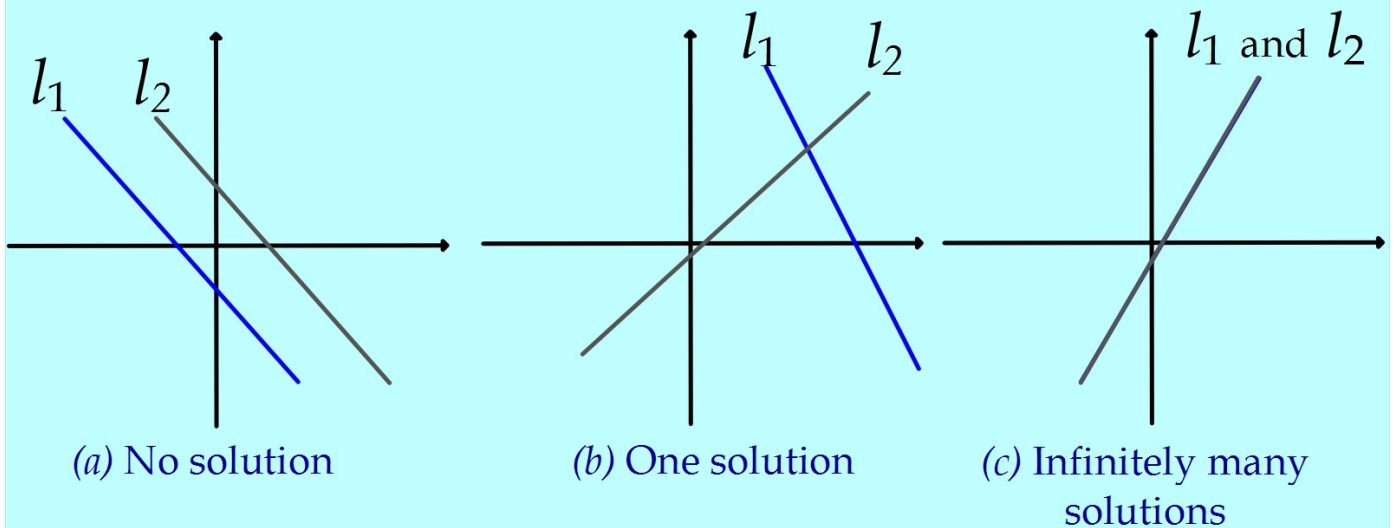


# Redundant, Inconsistent & Ill-conditioned Equations

"Explain what happens when ....."

# Linear Systems

We have considered only two equations with two unknowns in the past, and will now show that the same three possibilities hold for arbitrary linear systems:



*Every system of linear equations has no solutions, or has exactly one solution, or has infinitely many solutions.*

# Redundancy

## Example

Solve the system of equations:

$$\begin{aligned}x + y + z &= 6 \\2x + y - 2z &= -2 \\3x + 2y - z &= 4\end{aligned}$$

$$\begin{array}{ccc|c} 1 & 1 & 1 & 6 \\ 2 & 1 & -2 & -2 \\ 3 & 2 & -1 & 4 \end{array} \begin{array}{l} R_1 \\ R_2 \\ R_3 \end{array}$$

$$\begin{array}{l} R_2 \rightarrow R_2 - 2R_1 \\ R_3 \rightarrow R_3 - 3R_1 \end{array} \begin{array}{ccc|c} 1 & 1 & 1 & 6 \\ 0 & -1 & -4 & -14 \\ 0 & -1 & -4 & -14 \end{array}$$

$$R_3 \rightarrow R_3 - R_2 \begin{array}{ccc|c} 1 & 1 & 1 & 6 \\ 0 & -1 & -4 & -14 \\ 0 & 0 & 0 & 0 \end{array}$$

The row of zeros gives no information and tells us that there is not a unique solution for  $z$ . (i.e.  $z$  can take any value).

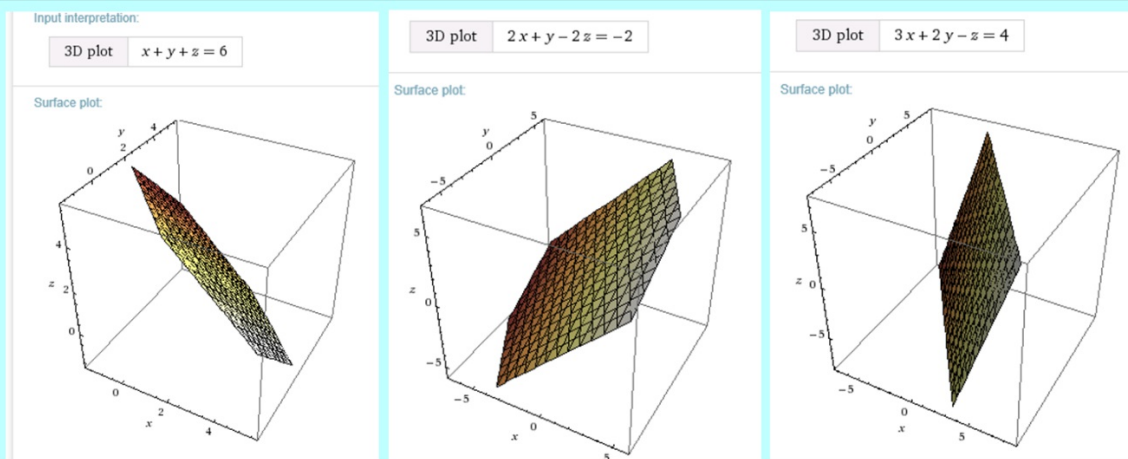
Let  $z = t$  (where  $t$  is any real number)

$$\begin{aligned} \text{From } R_2: \quad -y - 4z &= -14 \quad (z = t) \\ y &= 14 - 4t \end{aligned}$$

$$\begin{aligned} \text{From } R_1: \quad x + y + z &= 6 && (y = 14 - 4t \text{ and } z = t) \\ x + (14 - 4t) + t &= 6 \\ x &= 3t - 8 \end{aligned}$$

Hence solution can be written  $x = 3t - 8, y = 14 - 4t, z = t$

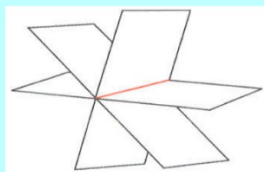
A general solution as shown above is usually given for redundancy.



These equations give points that all lie on a straight line  
*(see Vectors Unit 3).*

The system of equations has an infinite number of solutions.

There are, really, only two equations, & the 3rd is **redundant**.



# Inconsistent

## Example

Solve the system of equations:

$$\begin{aligned}x + y + z &= 6 \\2x + y - 2z &= -2 \\3x + 2y - z &= 3\end{aligned}$$

$$\begin{array}{ccc|c} 1 & 1 & 1 & 6 \\ 2 & 1 & -2 & -2 \\ 3 & 2 & -1 & 3 \end{array} \begin{array}{l} R_1 \\ R_2 \\ R_3 \end{array}$$

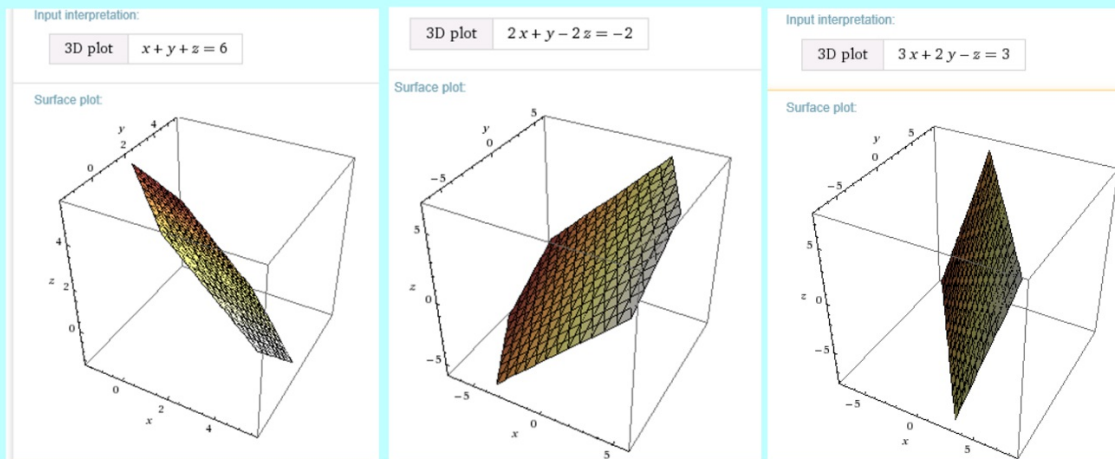
$$\begin{array}{l} R_2 \rightarrow R_2 - 2R_1 \\ R_3 \rightarrow R_3 - 3R_1 \end{array} \begin{array}{ccc|c} 1 & 1 & 1 & 6 \\ 0 & -1 & -4 & -14 \\ 0 & -1 & -4 & -15 \end{array}$$

$$R_3 \rightarrow R_3 - R_2 \begin{array}{ccc|c} 1 & 1 & 1 & 6 \\ 0 & -1 & -4 & -14 \\ 0 & 0 & 0 & -1 \end{array}$$

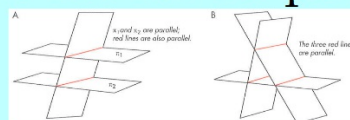


From  $R_3$  we get  $0z = -1$  which is clearly impossible.

Hence there is no solution.



**Inconsistency** means that there are no values of  $x, y, z$  which satisfy all three equations. It arises when three planes, given by the 3 equations, do not have a point in common.



## Ill-conditioning

All our calculations so far have been exact. However, in many real-life problems using experimental or collected data, the coefficients in the equations are often rounded to the nearest integer, 1 d.p., etc.

### Example

Consider these results from an experiment:

$$\begin{array}{ll} x + 1000y = 1 & x + 999y = 1 \\ x + 999y = 2 & x + 1000y = 2 \end{array}$$

$$\begin{aligned}x + 1000y &= 1 \\x + 999y &= 2\end{aligned}$$

$$\begin{aligned}x + 999y &= 1 \\x + 1000y &= 2\end{aligned}$$

$$\begin{pmatrix} 1 & 1000 & 1 \\ 1 & 999 & 2 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 999 & 1 \\ 1 & 1000 & 2 \end{pmatrix}$$

$$R_2 - R_1 \begin{pmatrix} 1 & 1000 & 1 \\ 0 & -1 & 1 \end{pmatrix}$$

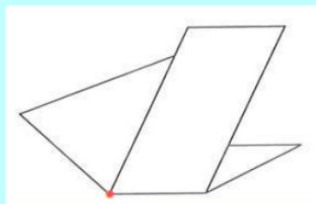
$$R_2 - R_1 \begin{pmatrix} 1 & 999 & 1 \\ 0 & 1 & 1 \end{pmatrix}$$

$$\text{Sol}^n \text{ is } x = 1001, y = -1$$

$$\text{Sol}^n \text{ is } x = -998, y = 1$$

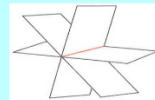
Where a system of eq<sup>n</sup>s show ill-conditioning no confidence can be put on the results obtained and is not a good model for real-life contexts.

## Summary



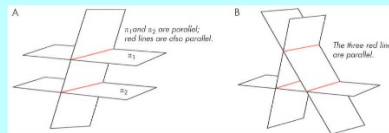
### Redundant:

When the second and third rows are the same i.e. redundant (provides no further information) there is an infinite number of solutions.



### Inconsistent:

When no solutions exist i.e.  $0z = 6$ .



### Ill-conditioned:

Disproportionate effects to results as a result of small changes to coefficients of  $x$ ,  $y$  and  $z$ .